Brushless DC Motor Systems

AXH Series

The **AXH** Series combines a compact, brushless DC speed control motor and 24 VDC board-level driver. These systems provide space savings and high power output, and are easy to use.

Combination Type (Pre-assembled Gearmotors)

The combination type (pre-assembled gearmotors) come with the motor and its dedicated gearhead already assembled. This simplifies installation in equipment.

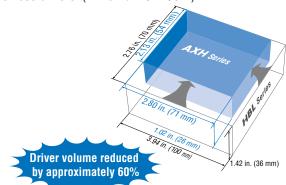
Motors and gearheads are also available separately so they can be on hand to make changes or repairs.

* Except for 15W type

Features

Compact Board-Level Driver

The size of the **AXH** driver has been reduced by approximately 60% when compared to conventional DC brushless drivers. (Driver for 15W-50W)



Compact, High Power Motors

The size of the **AXH** Motor has been reduced by approximately 55% when compared to conventional AC speed control motors [\square 3.15 in. (\square 80mm) size]. The motor has extremely high output power for its small size.

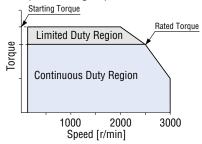
Superior Speed Stability

The fluctuation is only $\pm 1\%$ for load, voltage and temperature. These motors provide superior speed stability with minimal speed fluctuation.



Constant Torque over a Wide Speed Range

The speed can be set within the wide range of 100 r/min to 3000 r/min (30:1). The **AXH** Series maintains a constant torque from low speed to high speed.



Gearheads Provide High Torque

AXH geared type motors come pre-assembled with a gearhead. These gearheads provide torque up to 17.7 lb-in (2N·m) for the 15 W motors and up to 141 lb-in (16N·m) with the 50 W motors.

Protective Functions

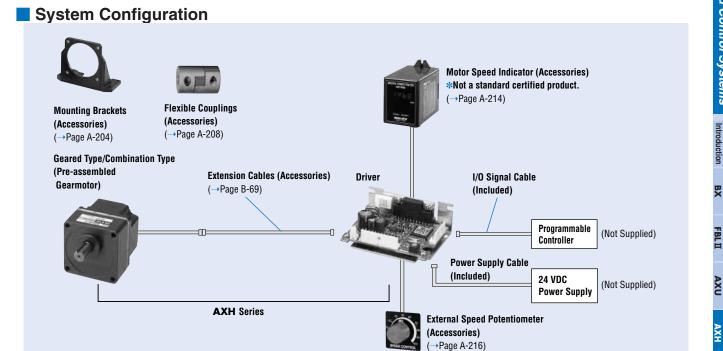
The **AXH** Series is equipped with protective functions to handle overload, overvoltage, undervoltage, overspeed and out-of-phase power. When one of these protective functions detects an abnormality, a LED blinks and motor comes to a stop.

Safety Standards and CE Marking

| Standards | | Certification Body | Standards File No. | CE Marking | |
|----------------------------|--------------------|--------------------|--------------------|----------------|--|
| AXH015 type | UL1950 | | | | |
| AXH230 type AXH450 type | CSA C22.2 No.950 | UL | E208200 | EMC Directives | |
| AYUS 100 type | UL60950 | UL | E208200 | | |
| AXH5100 type | CSA C22.2 No.60950 | UL | L200200 | | |

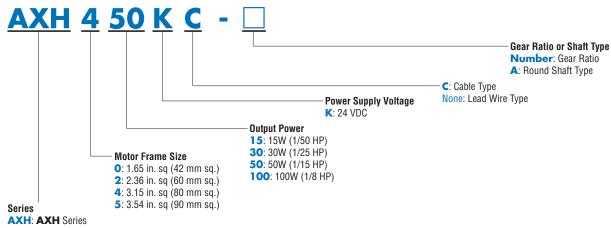
- When the system is approved under various safety standards, the model names on the motor and driver nameplates are the approved model names.
- List of Motor and Driver Combinations→Page B-68
- Details of Safety Standards→Page G-2
- The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the
 motor/driver incorporated in the equipment.

AC Motor Systems



The system configuration shown is an example. Other configurations are available.





Product Line

Geared Type/Combination Type

| Output | Power | Model | Gear Ratio |
|--------|-------|------------|------------------------------------|
| HP | W | Wodor | dour riano |
| 1/50 | 15 | AXH015K-□ | 5,10, 15, 20, 30, 50, 100 |
| 1/25 | 30 | AXH230KC-□ | 5, 10, 15, 20, 30, 50, 100, 200 |
| 1/15 | 50 | АХН450КС-□ | 5, 10, 15, 20, 30, 50, 100, 200 |
| 1/8 | 100 | AXH5100KC- | 5, 10, 15, 20, 30, 50, 100, 200 |

AXHO15K — are Geared Type and the others are combination type.

Round Shaft Type

| Output HP | Power W | Model |
|--------------|------------|-------------|
| 1/50 | 15 | AXH015K-A |
| 1/25 | 30 | AXH230KC-A |
| 1/15 | 50 | AXH450KC-A |
| 1/8 | 100 | AXH5100KC-A |

Enter the gear ratio in the box (□) within the model name.

Specifications



| Model Gea | ared Type/Combination Type | AXH015K-□ | AXH230KC-□ | AXH450KC-□ | AXH5100KC-□ | | |
|-------------------|---|--|----------------------------|----------------------------------|-------------|--|--|
| Model | Round Shaft Type | AXH015K-A | AXH230KC-A | AXH450KC-A | AXH5100KC-A | | |
| Rated Output Pow | ver HP (W) | 1/50 (15) | 1/25 (30) | 1/15 (50) | 1/8 (100) | | |
| Power Source | Voltage | | 24 VDC | ±10% | | | |
| | Rated Input Current A | 1.0 | 2.1 | 3.1 | 6.0 | | |
| | Maximum Input Current A | 2.0 | 3.5 | 5.0 | 9.0 | | |
| Rated Torque | oz-in (N·m) | 7.1 (0.05) | 17 (0.12) | 28 (0.20) | 56 (0.40) | | |
| Starting Torque | oz-in (N·m) | 10.6 (0.075) | 21 (0.15) | 34 (0.24) | 71 (0.50) | | |
| Permissible Load | Inertia J * oz-in ² (×10 ⁻⁴ kg·m ²) | 2.7 (0.5) | 9.8 (1.8) | 18.1 (3.3) | 31 (5.6) | | |
| Maximum Speed | r/min | 3000 | | | | | |
| Rated Speed | r/min | 3000 | | 2500 | | | |
| Variable Speed Ra | ange r/min | 100~3000 (30:1) | | | | | |
| | Load | ±1% Max. (0~rated torque, at rated speed) | | | | | |
| Speed Regulation | Voltage | $\pm 1\%$ Max. (Power supply voltage $\pm 10\%$, at rated speed with no load) | | | | | |
| | Temperature | <u>+</u> | 1% Max. (32°F~122°F [0°C~+ | 50°C] at rated speed with no loa | ad) | | |

- * The permissible load inertia specified above is only applicable for round shaft type. Permissible Load Inertia for Geared Type and Combination Type → Page B-61
- Enter the gear ratio in the box (\square) with the model name.
- The values for each item is for the motor only.

Common Specifications

| Item | Specifications | | | | | | | |
|---------------------------|---|--------------------------------------|-------------------------|--|--|--|--|--|
| Speed Control Method | Any one of the following methods. 1. By built-in potentiometer 2. By external potentiometer 3. By DC voltage $(0\sim5 \text{ VDC})$ | | | | | | | |
| | C-MOS negative logic | L: (ON): 0~0.5 VDC | H: (OFF): 4~5 VDC | | | | | |
| | START/STOP input | L: START | H: STOP | | | | | |
| Innut Cianala | Brake input | L: RUN | H: Instantaneous stop | | | | | |
| Input Signals | Direction of rotation input | L: CW | H: CCW | | | | | |
| | Speed setting method | L: Internal | H: External | | | | | |
| | Alarm reset | L: Reset | H: Normal | | | | | |
| Output Cianala | Open collector output External use conditions 26.4 VDC, 10 mA Max. | | | | | | | |
| Output Signals | Speed Signal Output (SPEED OUT) 30 P/R, Alarm Signal Output (ALARM OUT) | | | | | | | |
| | When the following are activated, the alarm sigr | al will be output and the motor will | come to a natural stop. | | | | | |
| | • Overload Protection: Activated when a load exceeding the rated torque is applied to the motor for approximately 5 seconds or more. | | | | | | | |
| Protection Functions *1 | Out-of-Phase Protection: Activated when the sensor wire inside the motor cable is disconnected. | | | | | | | |
| 1 Totection Functions | Overvoltage Protection: Activated when the voltage applied to the driver exceeds 24 VDC by approximately 15% or more. | | | | | | | |
| | Undervoltage Protection: Activated when the voltage applied to the driver falls at least 25% below 24 VDC. | | | | | | | |
| | Over Speed Protection: Activated when the motor rotates at an abnormal speed above 3500 r/min. | | | | | | | |
| Motor Insulation Class *2 | | Class E [248°F (120°C)] | | | | | | |
| Rating | | Continuous | | | | | | |

^{*1} With the **AXH** Series the motor speed cannot be controlled in applications where the motor shaft is turned by the load, as in lowering operations.

Also, the motor will stop naturally if the load exceeds the permissible load inertia or the overvoltage protection function is activated during load lowering operations.

*2 Motor insulation is recognized as class A [221°F(105°C)] by UL and CSA standards.

General Specifications

| Item | Motor | Driver | | | | |
|-----------------------|---|---|--|--|--|--|
| Insulation Resistance | $100\ M\Omega$ or more when 500 VDC megger is applied between the windings and the frame after continuous operation under normal ambient temperature and humidity. | $100~\text{M}\Omega$ or more when 500 VDC megger is applied between the power supply input and the frame after continuous operation under normal ambient temperature and humidity. | | | | |
| Dielectric Strength | Sufficient to withstand 0.5 kVAC at 50 Hz applied between the windings and the frame for 1 minute after continuous operation under normal ambient temperature and humidity. | Sufficient to withstand 0.5 kVAC at 50 Hz applied between the power supply input and the frame for 1 minute after continuous operation under normal ambient temperature and humidity. | | | | |
| Temperature Rise | 90°F (50°C) or less measured by the thermocoupler method after the temperature of the coil has stabilized under normal operation at the rated voltage and frequency under normal ambient temperature and humidity, with a connected gearhead or equivalent heat radiation plate.* | _ | | | | |
| Ambient Temperature | 32°F~122°F (0°C~- | +50°C) (nonfreezing) | | | | |
| Ambient Humidity | 85% maximum (| (noncondensing) | | | | |
| Atmosphere | No corrosive gases or dust | | | | | |
| Degree of Protection | 15W Type: IP 40 30W~100W Type: IP65 (except for the mounting surface) | IP 00 | | | | |

^{*} Size of heat radiation plate (Material: Aluminum)

AXH230KC-A: 4.53 in. × 4.53 in. (115 mm × 115 mm), 0.20 in. (5 mm) thick **AXH450KC-A**: 5.31 in. × 5.31 in. (135 mm × 135 mm), 0.20 in. (5 mm) thick **AXH5100KC-A**: 7.87 in. × 7.87 in. (200 mm × 200 mm), 0.20 in. (5 mm) thick

BX

| Ge | Gearmotor — Torque Table (Geared Type/Combination Type) Unit = Upper values: Ib-in/Lower values: N-1 | | | | | | | | | | |
|-------|---|--------------------|--------------------|----------------------|------------------|---------------------|----------------|----------------|----------|--|--|
| Model | Speed Range * r/min | 20~500 (20~600) | 10~250 (10~300) | 6.7~167 (6.7~200) | 5~125 (5~150) | 3.3~83 (3.3~100) | 2~50 (2~60) | 1~25 (1~30) | 0.5~12.5 | | |
| | Gear Ratio | 5 | 10 | 15 | 20 | 30 | 50 | 100 | 200 | | |
| | | 0.0 | 0.0 | 0.0 | 7.0 | 44.5 | 477 | 477 | _ | | |

| Model | Speed Range * r/min | (20~600) | (10~300) | (6.7~200) | (5~150) | (3.3~100) | (2~60) | (1~30) | 0.5~12.5 |
|-------|---------------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-----------|
| | Gear Ratio | 5 | 10 | 15 | 20 | 30 | 50 | 100 | 200 |
| AXH01 | 5K-□ | 2.0 0.23 | 3.9 0.45 | 6.0 0.68 | 7.6 0.86 | 11.5 1.3 | 17.7 2.0 | 17.7 2.0 | _ |
| AXH23 | окс-□ | 4.7 0.54 | 9.7 1.1 | 14.1 1.6 | 19.4 2.2 | 27 3.1 | 46 5.2 | 53 6.0 | 53 6.0 |
| AXH45 | окс-□ | 7.9 0.9 | 15.9 1.8 | 23 2.7 | 31 3.6 | 46 5.2 | 76 8.6 | 141 16 | 141 16 |
| AXH51 | 00КС-□ | 15.9 1.8 | 31 3.6 | 47 5.4 | 63 7.2 | 91 10.3 | 152 17.2 | 260 30 | 260 30 |

ullet Enter the gear ratio in the box (\square) within the model name.

Permissible Overhung Load and Permissible Thrust Load

Geared Type/Combination Type

| Permissible Overhung Load | | | | | | | Thrust Load |
|---------------------------|------------|-----------------|-------------------|-----------------|-------------------|-----|-------------|
| Model | Gear Ratio | 0.39 in. (10 mm | n) from shaft end | 0.79 in. (20 mm | n) from shaft end | | |
| | | lb. | N | lb. | N | lb. | N |
| AXH015K-□ | 5~100 | 11.2 | 50 | _ | | | 30 |
| | 5 | 22 | 100 | 33 | 150 | | |
| AXH230KC-□ | 10∼20 | 33 | 150 | 45 | 200 | 9 | 40 |
| | 30∼200 | 45 | 200 | 67 | 300 | | |
| | 5 | 45 | 200 | 56 | 250 | | |
| AXH450KC-□ | 10∼20 | 67 | 300 | 78 | 350 | 22 | 100 |
| | 30∼200 | 101 | 450 | 123 | 550 | | |
| | 5 | 67 | 300 | 90 | 400 | | |
| AXH5100KC-□ | 10∼20 | 90 | 400 | 112 | 500 | 33 | 150 |
| | 30∼200 | 112 | 500 | 146 | 650 | | |

[•] Enter the gear ratio in the box () within the model name.

Round Shaft Type

| | Permissible Overhung Load | | | | | | |
|-------------|--------------------------------|-----|-----------------|------------------|--|--|--|
| Model | 0.39 in. (10mm) from shaft end | | 0.79 in. (20 mm |) from shaft end | | | |
| | lb. | N | lb. | N | | | |
| AXH015K-A | 11.2 | 50 | _ | _ | | | |
| AXH230KC-A | 15.7 | 70 | 22 | 100 | | | |
| AXH450KC-A | 27 | 120 | 31 | 140 | | | |
| AXH5100KC-A | 36 | 160 | 38 | 170 | | | |

Permissible Thrust Load: Avoid thrust loads as much as possible. If thrust load is unavoidable, keep it to no more than half the motor weight.

■ Permissible Load Inertia J for Geared Type/Combination Type

Unit = Upper values: oz-in 2 /Lower values: $\times 10^{-4}$ kg·m 2

| Model Gear Ratio | 5 | 10 | 15 | 20 | 30 | 50 | 100 | 200 |
|------------------|------------|------------|-----------|-----------|------------|-------------|-------------|-------|
| AXH015K-□ | 2.2 0.4 | 9.3 1.7 | 21 3.9 | 38 7.0 | 86 15.7 | 240 43.7 | 240 43.7 | _ |
| AXH230KC-□ | 8.5 | 34 | 77 | 136 | 310 | 850 | 850 | 850 |
| | 1.55 | 6.2 | 14.0 | 24.8 | 55.8 | 155 | 155 | 155 |
| AXH450KC-□ | 30 | 120 | 270 | 480 | 1080 | 3000 | 3000 | 3000 |
| | 5.5 | 22 | 49.5 | 88 | 198 | 550 | 550 | 550 |
| AXH5100KC-□ | 137 | 547 | 1230 | 2188 | 4923 | 13675 | 13675 | 13675 |
| | 25 | 100 | 225 | 400 | 900 | 2500 | 2500 | 2500 |

[•] Enter the gear ratio in the box (
) within the model name.

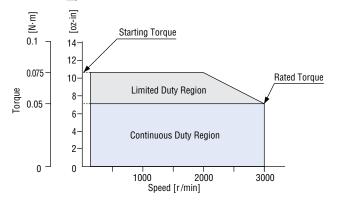
[•] A colored background indicates gear shaft rotation in the same direction as the motor shaft; a white background indicates rotation in the opposite direction.

^{*} Values inside parentheses () are for the **AXHO15K-** model.

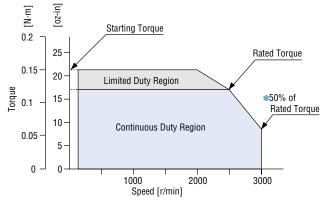
Speed — Torque Characteristics

- For the geared type and combination type, the values are for the motor alone.
- Enter the gear ratio in the box (□) within the model name.

AXH015K-\(\triangle / AXH015K-A)

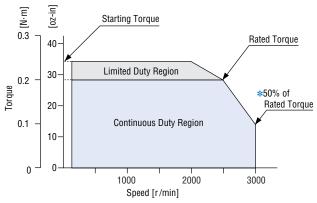


AXH230KC-\(\triangle / AXH230KC-A



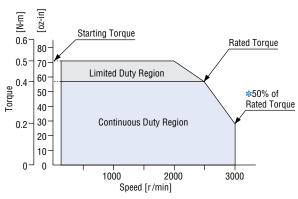
* Values for 24 VDC with no extension cable

AXH450KC-\(\subseteq\)/AXH450KC-A



* Values for 24 VDC with no extension cable

AXH5100KC-\(/AXH5100KC-A



* Values for 24 VDC with no extension cable

Dimensions Scale 1/4, Unit = inch (mm)

Mounting screws are included with the combination type. Dimensions for screws → Page B-133 Enter the gear ratio in the box (\Box) within the model name.

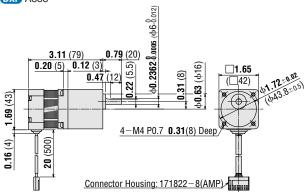
Motor/Gearhead

AXH015K-□ (Geared Type)

Geared motor: AXHM015K-□

Weight: 1.1 lb. (0.5 kg)

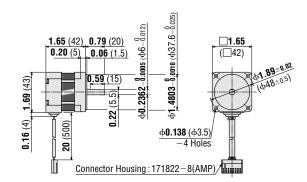
DXF A388



Round Shaft Type AXH015K-A

Motor: AXHM015K-A Weight: 0.55 lb. (0.25 kg)

DXF A389



BX

FBLII

AX UX

S

S

AC Motor Systems

Motor/Gearhead **AXH230KC-** (Combination Type) Lead Wire Types are also Motor: AXHM230KC-GFH available. Contact your Gearhead: GFH2G

Oriental Motor Representative for more information.

Round Shaft Type AXH230KC-A

 Φ **2.1260.**0.0012 $(\Phi$ 54-0.030)

 ϕ **0.3150**-0.0006 $(\phi$ 8-0.015)

Motor: AXHM230KC-A Weight: 1.1 lb. (0.5 kg) **DXF** A295U

.65

(42)

0.31

(8)

Cable

2.36

(24)

0.08

(2)

20 inch (500 mm) Length

5

Lead Wire Types are also available. Contact your Oriental Motor Representative for more information.

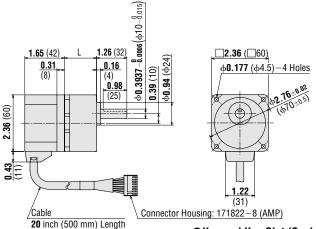
□2.36 (□60),

φ**0.177** (φ4.5)

1.22

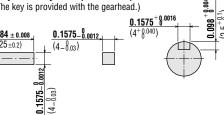
Connector Housing: 171822-8 (AMP)

4 Holes



■Key and Key Slot (Scale 1/2)

(The key is provided with the gearhead.)



0.984 ± 0.008 (25±0.2)

Motor/Gearhead

AXH450KC- (Combination Type)

 $AXH230KC-5\sim20$: L = 1.34 (34)

AXH230KC-200: L = 1.69 (43)

AXH230KC-30 \sim 100: L = 1.50 (38)

Weight (including gearhead): 2.2 lb. (1.0 kg)

A294BU (GFH2G30~100) A294CU (GFH2G200)

DXF A294AU (GFH2G5~20)

Motor: AXHM450KC-GFH Gearhead: GFH4G□

Weight (including gearhead): 4.0 lb. (1.8 kg)

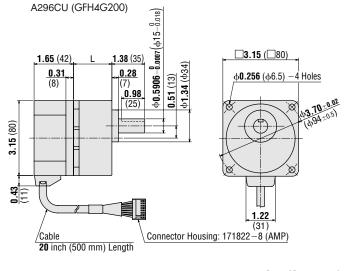
DXF A296AU (GFH4G5~20) A296BU (GFH4G30~100) Lead Wire Types are also available. Contact your Oriental Motor Representative for more information.

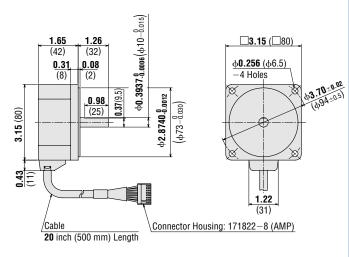
Round Shaft Type AXH450KC-A

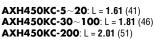
Motor: AXHM450KC-A Weight: 1.76 lb. (0.8 kg)

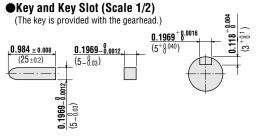
DXF A297U

Lead Wire Types are also available. Contact your Oriental Motor Representative for more information.









Motor/Gearhead

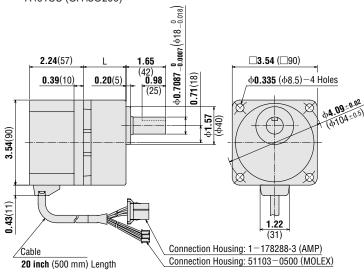
AXH5100KC-□ (Combination Type)

Motor: AXHM5100KC-GFH Gearhead: GFH5G□

Weight (including gearhead): 6.4 lb. (2.9 kg)

DXF A401AU (GFH5G5~20)

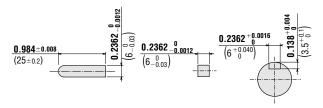
A401BU (GFH5G30~100) A401CU (GFH5G200)



AXH5100KC-5~20: L = 1.77 (45) **AXH5100KC-30~100**: L = 2.28 (58) **AXH5100KC-200**: L = 2.52 (64)

●Key and Key Slot (Scale 1/2)

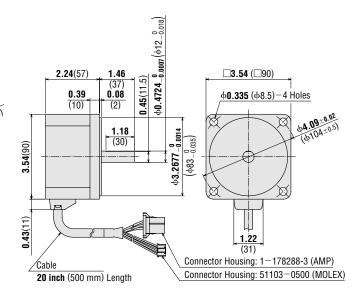
(The key is provided with the gearhead.)



Round Shaft Type AXH5100KC-A

Motor: AXHM5100KC-A Weight: 3.1 lb. (1.4 kg)

DXF A402U

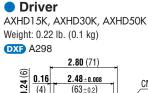


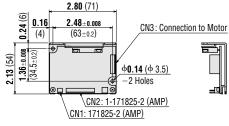
FBLII

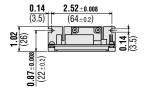
AX UX

AXE

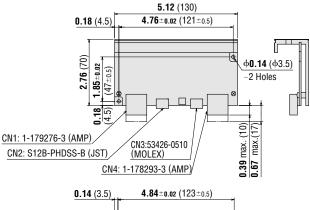
S

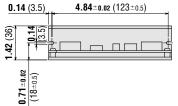






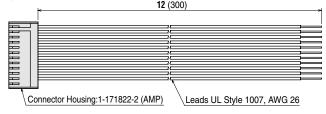
AXHD100K Weight: 0.66 lb. (0.3 kg) DXF A403





Driver Input Signal Cable (Included)

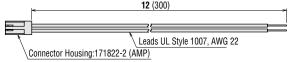
◆ For 15 W, 30 W, 50 W



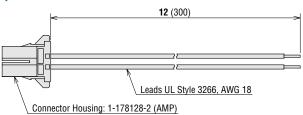
For 100 W 12 (300) Leads UL Style 1007, AWG 26 Connector Housing: PHDR-12VS (JST)

Driver Power Supply Cable (Included)

◆ For 15 W, 30 W, 50 W



For 100 W



List of Motor and Driver Combinations

Geared Type/Combination Type

| Output Power | Model | Motor Model | Gearhead Model | Driver Model |
|--------------|------------|----------------|----------------|--------------|
| 1/50 HP 15 W | AXH015K-□ | AXHM015K-□* | _ | AXHD15K |
| 1/25 HP 30 W | AXH230KC-□ | AXHM230KC-GFH | GFH2G□ | AXHD30K |
| 1/15 HP 50 W | AXH450KC-□ | AXHM450KC-GFH | GFH4G□ | AXHD50K |
| 1/8 HP 100 W | AXH5100KC- | AXHM5100KC-GFH | GFH5G□ | AXHD100K |

- \bullet Enter the gear ratio in the box (\square) with in the model name.
- * Geared Motor Model

Round Shaft Type

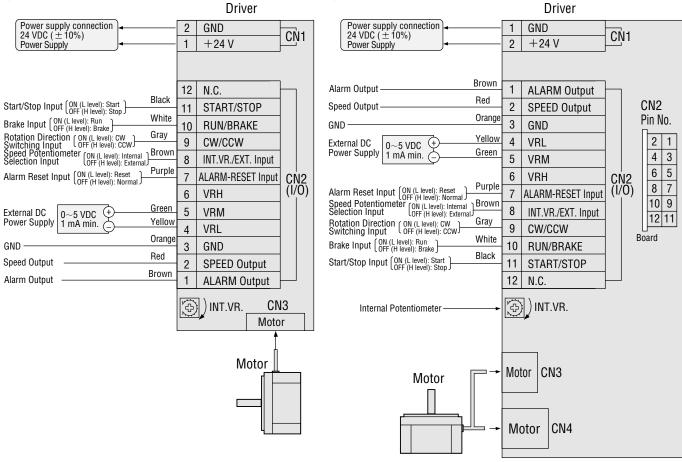
| Output Power | Model | Motor Model | Driver Model |
|--------------|-------------|--------------|--------------|
| 1/50 HP 15 W | AXH015K-A | AXHM015K-A | AXHD15K |
| 1/25 HP 30 W | AXH230KC-A | AXHM230KC-A | AXHD30K |
| 1/15 HP 50 W | AXH450KC-A | AXHM450KC-A | AXHD50K |
| 1/8 HP 100 W | AXH5100KC-A | AXHM5100KC-A | AXHD100K |

Connection and Operation

Connection Diagrams

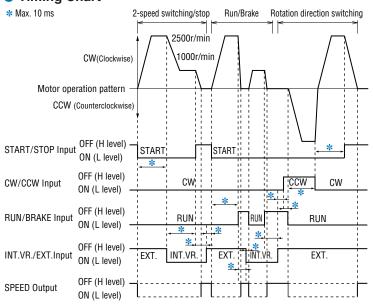






When the motor cable needs to be extended, use an optional extension cable [sold separately, 4.9 ft. (1.5 m)].
 Extension Cable → Page B-69

Timing Chart



- Run/stop, instantaneous stopping and rotation direction switching operations can all be controlled with the START/STOP, RUN/BRAKE and CW/CCW signals.
- If both the START/STOP signal and the RUN/BRAKE signal are set to ON (L level), the motor rotates. At this time, if the CW/CCW signal is set to ON (L level), then the motor rotates clockwise as seen from the motor shaft side; if the CW/CCW signal is set to OFF (H level), the motor rotates in the counterclockwise direction.
- If the RUN/BRAKE signal is set to OFF (H level) while the START/STOP signal is ON (L level), the motor stops instantaneously. If the START/STOP signal is set to OFF (H level) while the RUN/BRAKE signal is set to ON (L level), the motor stops naturally.
- Wait for 10 ms before switching the other input signals.
- Do not switch different input signals simultaneously.
 Wait for 10 ms before switching the other input signals.

B-66 System Configuration B-59 Specifications B-60 Characteristics B-62

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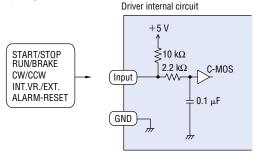
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AC Motor Systems

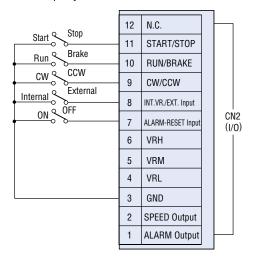
- Input Signal Circuit
- **♦ Input Circuit**



Example of Input Circuit Connection

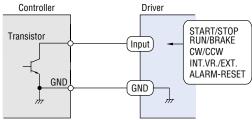
· Control by Small Capacity Relay, Switch, or Similar Device

Switch capacity: 24 VDC 10 mA

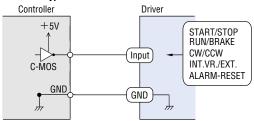


· Control by Controller

Transistor output type

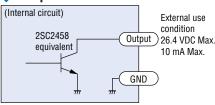


C-MOS type



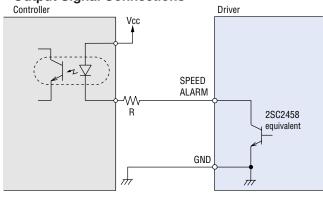
Output Signal Circuit

Output Circuit



♦ Example of Output Circuit Connection

· Output Signal Connections

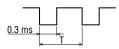


· SPEED Output

The system outputs pulse signals (with a width of 0.3 ms) at a rate of 30 pulses per rotation of the motor output shaft, synchronized with the motor drive. You can measure the SPEED output frequency and calculate the motor speed.

$$\mbox{Motor speed (r/min)} = \frac{\mbox{Speed output frequency [Hz]}}{30} \, \times \, \mbox{60 [r/min]}$$

SPEED output frequency (Hz) = $\frac{1}{T}$



· ALARM Output

The ALARM output is normally at the ON (L level) and switches to the OFF (H level) when there is an alarm.

· ALARM-RESET

When the motor is stopped, setting this signal to the ON (L level), then returning it to the OFF (H level) resets the alarm. Please return either the START/STOP input or the RUN/BRAKE input to the OFF (H level) before inputting the ALARM-RESET. The ALARM-RESET is not accepted if both these signals are at the ON (L level).

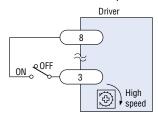
Notes:

- Output signal is open collector output, so an external power supply (Vcc) is required.
- Use a power supply of no more than 26.4 VDC and connect a limit resistance (R) so that the output current does not exceed 10 mA. When using neither the speed output function nor the alarm output function, this connection is not required.

Speed Setting Method

Speed Control by Internal Potentiometer

When INT.VR/EXT. input is set to the ON (L level), the speed can be set with the internal speed potentiometer. There is no need for this connection when the internal potentiometer is not used.

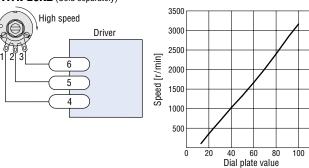


Speed Control by External Potentiometer

When separating the motor speed setting from the driver, connect the optional external potentiometer as follows.

External speed potentiometer

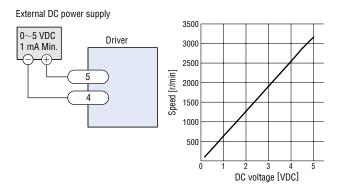
PAVR-20KZ (Sold separately)



External Potentiometer Scale—Speed Characteristics (Representative Values)

Speed Control by External DC Voltage

When setting the motor speed with an external DC voltage, do so in the following manner.



DC Voltage – Speed Characteristics (Representative Values)

Accessories (Sold Separately)

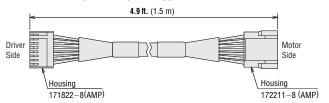
Extension Cable

The maximum extended length is 6.6 ft. (2 m).

For 15 W, 30 W, 50 W

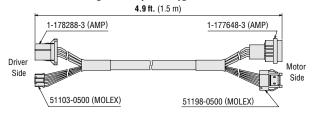
Two types of cables are available. Covered lead wire type and ribbon cable type.

CC02AXH [4.9 ft. (1.5 m)]



For 100 W

CC02AXH2 [4.9 ft. (1.5 m)]



• FCO2HBL [4.9 ft. (1.5 m)]

